

## ROBOTICS

# IRB 6660 Industrial Robot



#### The aptimised press tending robot:

The most critical robot axes have been reinforced according to typical price cycle time regularments. Whee combined with the parallel ann design it makes the robot stiffer, easier to control and faster.

The robot's gears have been reinforced to extend their life time and improve how they function at faster speeds. It also includes prover and resolver cables up to the upper arm house, which makes leteration of an external axis easier.

#### The pre-machining robet

High productivity is machining applications requires a stiff and robust robot. The HR 6550 has a parallel arm structure, and in general, a very compact and sturdy rescherical design. As special dual boaring design and powerful gears and motors provide additional support for handing fluctuating process forces corrector within applications such as milling, deburring and principle.

The IRB 6660 is an extremely reliable robot designed for high performance applications. The stiff design supports accuracy and short cycle times, which in the end increases productivity. It comes in three versions, two with long reach almed at high-performance press tending operations and the third designed for challenging applications like machining of castings.

The robot is available with ABB's Foundry Plus 2 protection and also has dedicated cable protection to further strengthen the reliability and optime.

#### RobotWare Hachining Force Control

This software product provides improved process results and quality – secure controlled contact force to grinding application gives improved and consistent product suests.

#### Malin Applications

- Preparationed firest
- Machine tending
- Machining.
- Intribution
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- e Carbridgeon
- Searches

# **Abb Robot Programming Manual Irb 664**

**Brendan G. Carr** 

**Abb Robot Programming Manual Irb 664:** 

## Decoding **Abb Robot Programming Manual Irb 664**: Revealing the Captivating Potential of Verbal Expression

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